Slide 1

Administrivia

- (None.)

Slide 2

Memory Management — Overview

- One job of operating system is to “manage memory” — assign sections of main memory to processes, keep track of who has what, protect processes’ memory from other processes.
- As with CPU scheduling, we’ll look at several schemes, starting with the very simple. For each scheme, think about how well it solves the problem, how it compares to others.
- As with processes, there’s a tradeoff between simplicity and providing a nice abstraction to user programs.

Slide 3

Simple Schemes — No Abstraction

- Memory (a.k.a. “RAM”) can be thought of as a very long list of numbered cells (usually bytes).
- Simplest schemes for managing it don’t try to hide that view. (Names for these come from older edition of Tanenbaum’s book.)

Slide 4

Monoprogramming

- Idea — only one user program/process at a time, no swapping or paging. Only decision to make is how much memory to devote to o/s itself, where to put it.
- Consider tradeoffs — complexity versus flexibility, efficient use of memory.
- Used in very early mainframes, MS-DOS; still used in some embedded systems.

Slide 5

Multiprogramming With Fixed Partitions

- Idea — partition memory into fixed-size “partitions” (maybe different sizes), one for each process. Possibly also add the ability to “swap” programs (write their memory to disk, read back in later).
- Limits “degree of multiprogramming” (how many processes can run concurrently).
- Probably necessitates admissions scheduling — either one input queue per partition, or one combined queue.

  If one combined queue, how to choose from it when a partition becomes available? first job that fits? largest job that fits? etc.
- Consider tradeoffs — complexity versus flexibility, efficient use of memory.
- Used in early mainframes.

Slide 6

Multiprogramming With Variable Partitions

- Idea — separate memory into partitions as before, but allow them to vary in size and number.

  I.e., “contiguous allocation” scheme.
- Like previous scheme, necessitates admissions scheduling.
- Requires that we keep track of locations and sizes of processes’ partitions, free space. Notice potential for memory fragmentation.
- Consider tradeoffs — complexity versus flexibility, efficient use of memory.
- Used in early mainframes.

Slide 7

Program Relocation and Memory Protection

- At the machine-instruction level, references to memory are in terms of an absolute number. Some references are made relative to the program counter, but others may be absolute — i.e., generated when the program is translated to machine language. Compilers/assemblers can generate these only by making assumption about where program will reside in memory.
- In the very early days, all programs loaded at address 0, so no problem. With monoprogramming, too, all programs reside at the same address, so no problem.
- What happens, though, if you want to have multiple programs in memory? compilers/assemblers can't generate correct absolute addresses. Also, we want to protect each process's memory from other processes.

Slide 8

Program Relocation and Memory Protection, Continued

- One solution to relocation problem — generate, as part of the executable, a list of locations where there's an absolute address, and modify it as the program is loaded into memory. (What implications does this have for being able to do swapping?)
- One solution to the memory-protection problem — storage-protection keys (IBM 360, an early mainframe).
- A better solution to both problems involves translating addresses "on the fly" . . .

Slide 9

Sidebar: The "Address Space" Abstraction

- Basic idea is somewhat analogous to process abstraction, in which each process has its own simulated CPU. Here, each process has its own simulated memory.
- As with processes, implementing this abstraction is part of what an operating system can/should do.
- Usually, though, o/s needs help from hardware . . .

Slide 10

Dynamic Address Translation

- Underlying idea — separate program addresses (relative to start of program's "address space") from physical addresses (memory locations), and map program addresses to physical addresses. Also try to identify out-of-bounds addresses.
- Only practical way to implement — hardware "memory management unit" that logically sits between the CPU and memory.

  Simplifying, CPU references program addresses, MMU turns them into physical addresses, generates interrupt if invalid.

Slide 11

A Simple MMU

- Idea — map each process's address space to a contiguous chunk of real memory, based on base and limit addresses (B and L):

  Program address p maps to memory location $B + p$.

  If $B + p > L$, invalid (out of bounds).

  If B and L are different for each process — solves both problems.
- Turn this into hardware (MMU) by using base and limit registers.
- Solves both the relocation and protection problems, though may not be especially fast.
- Consider tradeoffs — complexity versus flexibility.
- Used in some early mainframes and PCs.

Slide 12

Memory Management with Contiguous Allocation

- Simplest MMU uses two registers, base and limit. This more or less implies that each process can have only one contiguous chunk of memory. (Notice here the interaction between hardware design and o/s design.)
- Key issues here are keeping track of what space is used by what, and deciding how to assign memory to processes.

Slide 13

Multiprogramming With Variable Partitions — Bitmaps

- One solution to problem of keeping track of locations/sizes of processes' memory and free-space "chunks".
- Idea — divide memory into "allocation units"; for each, one bit says whether it's free.
- Tradeoffs — simple? easy/quick to find free space of size N?
- How big should allocation units be? (What if they're really small? really big?)
- We've left something out here — how to keep track of processes' memory — where / how big. ?

Slide 14

Multiprogramming With Variable Partitions — Free List

- Another solution to problem of keeping track of locations/sizes of processes' memory and free-space "chunks".
- Idea — keep linked list with one entry for each process or free-space chunk ("hole"), sorted by address. When we allocate/free memory, possibly split/merge entries.
- Tradeoffs — simple? space requirements compared to bitmap?

Slide 15

Multiprogramming With Variable Partitions, Continued

- Another implementation issue — how to decide, when starting a process, which of the available free chunks to assign.
- Several strategies possible:
  - First fit.
  - Next fit.
  - Best fit.
  - Worst fit.
  - Quick fit.

Slide 16

Multiprogramming with Fixed/Variable Partitions — Recap

- Comparing the two schemes:
  - Similar admission scheduling issues.
  - Complexity versus flexibility, memory use also roughly similar.
- Either could be adequate for a simple batch system, maybe with the addition of swapping. (To be continued.)

Minute Essay

- None — sign in.