

# Points-To Analysis in Almost Linear Time

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## OUTLINE

### Ø INTRODUCTION

### Ø THE ALGORITHM

- The Source Language
- Types
- Typing Rules
- Stages of the Algorithm
- Processing Constraints
- Complexity

### Ø IMPLEMENTATION

### Ø RELATED WORK

### Ø CONCLUSION

## Points To Analysis In Linear Time

§ Paper Written by Bjarne Steensgaard (Microsoft Researcher)

§ Written in 1995 / Presented Jan. 1996

§ Flow Insensitive / Linear Time

§ Fastest Interprocedural Algorithm @ time of publication

§ Based on a NON-Standard Type System

## IMPORTANT ASPECTS OF THE RESEARCH

- A Type System for describing a universally valid storage shape graph (SSG) for a program in Linear Space...
- A Constraint System which gives the algorithm better results...
- A Linear Time Algorithm for POINTS-TO Analysis by solving a constraint system...

## THE SOURCE LANGUAGE

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THE SYNTAX OF THE LANGUAGE IS AS FOLLOWS:

```
S ::= x = y
      x = &y
      x = *y
      x = op(y1...yn)
      x = allocate(y)
      *x = y
      x = fun(f1...fn) → (r1...rm) S*
      x1...xm = p(y1...yn)
```

Figure 1: Abstract syntax of the relevant statements,  $S$ , of the source language.  $x, y, f, r$ , and  $p$  range over the (unbounded) set of variable names and constants.  $op$  ranges over the set of primitive operator names.  $S^*$  denotes a sequence of statements. The control structures of the language are irrelevant for the purposes of this paper.

**EXAMPLE OF FUNCTIONS IN THE LANGUAGE.....**

```
Add1 = fun(x) → ( r )
      xaddone = add(x 1)
      fi
result = Add1(99)
```

```
fact = fun(x) → ()
      if lessthan(x 1) then
        r = 1
      else
        minusone = subtract(x 1)
        nextfac = fact(minusone)
        r = multiply(x nextfac)
      fi
result = fact(10)
```

# TYPES

**TYPES OF THE LANGUAGE**

**NON-STANDARD SET OF TYPES**

•Types describe:

- Location of variables and locations created by dynamic allocations
- A Set of Locations as well as possible runtime contents of those locations

•A TYPE can be viewed as a NODE in a SSG (Storage Shape Graph)

The following productions describe our NONSTANDARD set of types used by our Points-To Analysis:

$$\begin{aligned} \alpha &::= \tau \times \lambda \\ \tau &::= \perp \mid \text{ref}(\alpha) \\ \lambda &::= \perp \mid \text{lam}(\alpha_1 \dots \alpha_n)(\alpha_{n+1} \dots \alpha_{n+m}) \end{aligned}$$

# TYPING RULES

## TYPING RULES

- Based on Non-Standard Set of Types
- Specify when a program is WELL-TYPED

**TYPING RULES (CONT'D.)**

Before introducing the typing rules we must present the notion of partial ordering and why it is important to the language's typing rules.....

"obvious" typing rule

$$\frac{A \vdash x : \text{ref}(\alpha) \quad A \vdash y : \text{ref}(\alpha)}{A \vdash \text{welltyped}(x = y)}$$

TYPING RULE (WPARTIAL ORDERING)

$$\begin{aligned} & t_1 \preceq t_2 \Leftrightarrow (t_1 = \perp) \vee (t_1 = t_2) \\ & (t_1 \times t_2) \preceq (t_3 \times t_4) \Leftrightarrow (t_1 \preceq t_3) \wedge (t_2 \preceq t_4). \end{aligned}$$

Given that non-pointers are represented by type  $\perp$ , the requirement can now be expressed by the following typing rule:

$$\frac{A \vdash x : \text{ref}(\alpha_1) \quad A \vdash y : \text{ref}(\alpha_2) \quad \alpha_2 \preceq \alpha_1}{A \vdash \text{welltyped}(x = y)}$$

### TYPING RULES

$\frac{A \vdash x : \text{ref}(a) \quad A \vdash y : \text{ref}(a) \quad \alpha : \mathbb{Q} \ a}{A \vdash \text{wtyp}(x = y)}$	$\frac{A \vdash x : \text{ref}(\text{ref}(x)) \quad A \vdash \text{wtyp}(x = \text{allocate}(y))}{A \vdash x : \text{ref}(\text{ref}(a)) \times \perp \quad A \vdash y : \text{ref}(a) \quad \alpha : \mathbb{Q} \ a}{A \vdash \text{wtyp}(x = y)}$
$\frac{A \vdash x : \text{ref}(\tau \times \perp) \quad A \vdash y : \tau}{A \vdash \text{wtyp}(x = \delta y)}$	<del><math display="block">\frac{A \vdash \text{ref}_i \times \text{lamb}(a_1 \dots a_n) (a_{n+1} \dots a_m) \quad A \vdash \tau : \text{ref}(a) \quad \alpha : \mathbb{Q} \ a}{A \vdash \text{wtyp}(x = \text{fun}(f_1 \dots f_n) \rightarrow (f_1 \dots f_n) \tau)}</math></del>
$\frac{A \vdash x : \text{ref}(a) \quad A \vdash y : \text{ref}(a) \quad \alpha : \mathbb{Q} \ a}{A \vdash \text{wtyp}(x = \text{ref}(\text{ref}(a)) \times \perp)}$	<del><math display="block">\frac{A \vdash y : \text{ref}(a) \quad \alpha : \mathbb{Q} \ a}{A \vdash \text{wtyp}(x = \text{fun}(f_1 \dots f_n) \rightarrow (f_1 \dots f_n) \tau)}</math></del>
$\frac{A \vdash x : \text{ref}(a) \quad A \vdash y : \text{ref}(a) \quad \forall i \in [1 \dots n] \ \alpha_i : \mathbb{Q} \ a_i}{A \vdash \text{wtyp}(x = \text{op}(f_1 \dots f_n))}$	$\frac{A \vdash y : \text{ref}(a_{12}) \quad A \vdash y : \text{ref}(a) \quad \forall i \in [1 \dots n] \ \alpha_i : \mathbb{Q} \ a_i \quad \forall j \in [1 \dots m] \ \alpha_{n+j} : \mathbb{Q} \ a_{n+j}}{A \vdash \text{wtyp}(x = \text{lamb}(a_1 \dots a_n) (a_{n+1} \dots a_m))}$

Figure 3: Type rules for the relevant statement types of the source language. All variables are assumed to have been associated with a type in the type environment  $A$ . (Distinct variables are assumed to have distinct names, so the type environment can describe all variables in all scopes simultaneously) “ $\perp$ ” is a wildcard value in the rules, imposing no restrictions on the type component it represents.

### EXPLANATION OF A STORAGE SHAPE GRAPH (SSG)

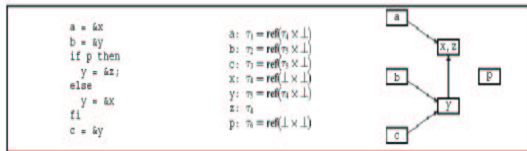


Figure 4: Example program, a typing of same that obeys the typing rules, and graphical representation of the corresponding storage shape graph. Note that variables  $x$  and  $z$  are described by the same type. Even though types  $\tau_1$  and  $\tau_5$  are structurally equivalent (as are  $\tau_2$  and  $\tau_3$ , and  $\tau_4$  and  $\tau_7$ ), they are not considered the same types.

**NOTE: TYPING SYSTEM ALLOWS ONLY ONE OUTGOING EDGE (TYPE VARIABLE CAN NOT BE ASSOCIATED WITH MORE THAN ONE TYPE)**

## ALGORITHM STAGES

### ALGORITHM STAGES

- Start w/ assumption that all variables are described by diff. types  
Initially type of all variables is :  $\text{ref}(\perp \times \perp)$ .  
Type Variable consists of an equivalence class representative (ECR) with associated type info.
- Merge Types as necessary to ensure WELL-TYPEDNESS  
Joining two types will NEVER make a statement that was well-typed no longer be well-typed...  
AND...when all program statements are WELL-TYPED, the program is WELL-TYPED

## PROCESSING CONSTRAINTS

Type of Constraint : Inequality Constraint ( $\neq$ )

If the “Left Hand Side” type variable is associated with type other than bottom, then two type variables MUST be joined to meet the constraint.

If “Left Hand Side” type variable is associated with “bottom”, then there is no need to join the two variables at this time...

## INFERENCE RULES

<pre> x = y; let ref(<math>\tau_1 \times \lambda_1</math>) = type(<math>\text{err}(x)</math>); let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(y)</math>); if (<math>\tau_1 \neq \tau_2</math> then <math>\text{qJoin}(\tau_1, \tau_2)</math>); if (<math>\lambda_1 \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_1, \lambda_2)</math>); x = &amp;y; let ref(<math>\tau_1 \times \lambda_1</math>) = type(<math>\text{err}(x)</math>); let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(y)</math>); if (<math>\tau_1 \neq \tau_2</math> then <math>\text{qJoin}(\tau_1, \tau_2)</math>); if (<math>\lambda_1 \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_1, \lambda_2)</math>); x = allocate(y); let ref(<math>\tau_1 \times \lambda_1</math>) = type(<math>\text{err}(x)</math>); let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(y)</math>); if (<math>\tau_1 \neq \tau_2</math> then <math>\text{qJoin}(\tau_1, \tau_2)</math>); if (<math>\lambda_1 \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_1, \lambda_2)</math>); x = y; let ref(<math>\tau_1 \times \lambda_1</math>) = type(<math>\text{err}(x)</math>); let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(y)</math>); if (<math>\tau_1 \neq \tau_2</math> then <math>\text{qJoin}(\tau_1, \tau_2)</math>); if (<math>\lambda_1 \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_1, \lambda_2)</math>); </pre>	<pre> x = fun(..., f, ...) -&gt; (..., f, ...) S? let ref(<math>\tau_1 \times \lambda_1</math>) = type(<math>\text{err}(x)</math>); if type(<math>\tau_1</math>) = <math>\perp</math>, then   settype(<math>\lambda_1</math>, lamb(<math>a_1 \dots a_n</math>) (<math>a_{n+1} \dots a_m</math>))   where     ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);     for <math>i \in [1 \dots n]</math> do       let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);       if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);       if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>);     else       let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);       for <math>i \in [1 \dots n]</math> do         let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);         if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);         if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>);       ...;       let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);       if type(<math>\tau_2</math>) = <math>\perp</math>, then         settype(<math>\lambda_1</math>, lamb(<math>a_1 \dots a_n</math>) (<math>a_{n+1} \dots a_m</math>))         where           for <math>i \in [1 \dots n]</math> do             let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);             if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);             if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>);           else             let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);             for <math>i \in [1 \dots n]</math> do               let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);               if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);               if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>);             ...;             let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);             if type(<math>\tau_2</math>) = <math>\perp</math>, then               settype(<math>\lambda_1</math>, lamb(<math>a_1 \dots a_n</math>) (<math>a_{n+1} \dots a_m</math>))               where                 for <math>i \in [1 \dots n]</math> do                   let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);                   if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);                   if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>);                 else                   let ref(<math>\tau_2 \times \lambda_2</math>) = type(<math>\text{err}(f)</math>);                   for <math>i \in [1 \dots n]</math> do                     let ref(<math>\tau_i \times \lambda_i</math>) = type(<math>\text{err}(a_i)</math>);                     if (<math>\tau_i \neq \tau_2</math> then <math>\text{qJoin}(\tau_i, \tau_2)</math>);                     if (<math>\lambda_i \neq \lambda_2</math> then <math>\text{qJoin}(\lambda_i, \lambda_2)</math>); </pre>
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Figure 5: Inference rules corresponding to the typing rules given in Figure 3.  $\text{err}(x)$  is the ECR representing the type of variable  $x$ , and  $\text{type}(\tau)$  is the type associated with the ECR.  $E$ .  $\text{qJoin}(\tau_1, \tau_2)$  performs the conditional join of ECRs  $\tau_1$  and  $\tau_2$ , and  $\text{settype}(\lambda, X)$  associates ECRs  $\lambda$  with type  $X$  and forces the conditional join with  $E$ .  $\text{MakeECR}(\tau)$  constructs a list of  $n$  new ECRs, each associated with the bottom type,  $\perp$ .



Project	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
linda-allcode	2				1										1
linda-assemble	2														
linda-lexer	1			1											
linda-computer					1										
linda-simulator	1	1								1					
linda-lexer2	1														
linda-lexer3	1			1											
linda-lexer4	1														
linda-lexer5	2														
linda-lexer6	1														
linda-lexer7	2														
linda-lexer8	1														
linda-lexer9	1														
linda-lexer10	1														
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linda-lexer97	1														
linda-lexer98	1														
linda-lexer99	1														
linda-lexer100	1														

Table 3

## Related Work

- Henglein - used type inference
- Weihl - points-to analysis is closest represented

## Related Work

Flow-sensitive analyses

- Chase and Ruf’s algorithm - interprocedural data give polynomial time
- Emami - Exponential time
- Wilson and Lam - Exponential Time

## Related Work

- Alias Analysis - Builds and maintains a list of access path expression that may evaluate to the same location.
- Context sensitive - Assumes runtime model that makes allocation regions explicit Related Work

## Related Work

- Andersen –
- Non-sensitive =  $O(A^2)$ , A is the # of abstract locations.
- Sensitive =  $O(A^4)$
- Compared to our solution, which is  $O(A)$

## Conclusion & Future

- Almost linear time
- Problems
- Future - Greater Precision
- Flow-sensitive
- Context-sensitive