Administrivia

- Homework 2 on the Web. Due in a week.
- Quiz 2 Monday. Topics will come from the parts of chapter 2 we've talked about through Friday.

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Mutual Exclusion Solutions So Far

- Solutions so far have some problems: inefficient, dependent on whether scheduler/etc. guarantees fairness.
- Also, they're very low-level, so might be hard to use for more complicated problems.

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• So, people have proposed various "synchronization mechanisms" . . .

Sidebar: Shared Memory and Synchronization

Solutions that rely on variables shared among processes assume that
assigning a value to a variable actually changes its value in memory (RAM),
more or less right away. Fine as a first approximation, but reality may be more
complicated, because of various tricks used to deal with relative slowness of
accessing memory:

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Optimizing compilers may keep variables' values in registers, only reading/writing memory when necessary to preserve semantics.

Hardware may include cache, logically between CPU and memory, such that memory read/write goes to cache rather than RAM. Different CPUs' caches may not be in synch.

Sidebar: Shared Memory and Synchronization, Continued

So, actual implementations need notion of "memory fence" — point at which
all apparent reads/writes have actually been done. Some languages provide
standard ways to do this; others (e.g., C!) don't. C's volatile ("may be
changed by something outside this code") helps some but may not be
enough.

Semaphores

- History 1965 paper by Dijkstra (possibly earlier work by Iverson, of APL/J fame).
- Idea define semaphore ADT:
 - "Value" non-negative integer.
 - Two operations, both atomic:
 - * up (V) add one to value.
 - * down (P) block until value is nonzero, then subtract one.
- Ignoring for now how to implement this is it useful?

Mutual Exclusion Using Semaphores

• Shared variables:

```
semaphore S(1);
```

Pseudocode for each process:

```
while (true) {
    down(S);
    do_cr();
    up(S);
    do_non_cr();
}
```

Invariant: "S has value 1 exactly when no process in its critical region, 0
exactly when one process in its critical region, and never has values other
than 0 or 1."

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Mutual Exclusion Using Semaphores, Continued

Invariant again: "S has value 1 exactly when no process in its critical region, 0
exactly when one process in its critical region, and never has values other
than 0 or 1."

Obvious (?) that this means first requirement is met. Can check that others are met too.

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Bounded Buffer Problem

- (Example of slightly more complicated synchronization needs.)
- Idea we have a buffer of fixed size (e.g., an array), with some processes ("producers") putting things in and others ("consumers") taking things out. Synchronization:
 - Only one process at a time can access buffer.
 - Producers wait if buffer is full.
 - Consumers wait if buffer is empty.
- Example of use: print spooling (producers are jobs that print, consumer is printer actually could imagine having multiple printers/consumers).

Bounded Buffer Problem, Continued

• Shared variables:

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- Synchronization requirements:
 - 1. At most one process at a time accessing buffer.
 - 2. Never try to get from an empty buffer or put to a full one.
 - 3. Processes only block if they "have to".

Bounded Buffer Problem, Continued

- We already know how to guarantee one-at-a-time access. Can we extend that?
- Three situations where we want a process to wait:
 - Only one get/put at a time.
 - If B is empty, consumers wait.
 - If B is full, producers wait.

Bounded Buffer Problem, Continued

- What about three semaphores?
 - One to guarantee one-at-a-time access.
 - One to make producers wait if B is full so, it should be zero if B is full "number of empty slots"?
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- One to make consumers wait if B is empty so, it should be zero if B is empty — "number of slots in use"?

Bounded Buffer Problem — Solution

• Shared variables:

up(full);

```
semaphore mutex(1);
    semaphore empty(N);
    semaphore full(0);
Pseudocode for producer:
                           Pseudocode for consumer:
while (true) {
                           while (true) {
                               down(full);
    item = generate();
    down(empty);
                               down(mutex);
    down(mutex);
                               item = get(B);
    put(item, B);
                               up(mutex);
    up(mutex);
                               up(empty);
```

}

use(item);

buffer B(N); // empty, capacity N

Implementing Semaphores

- We want to define:
 - Data structure to represent a semaphore.
 - Functions up and down.

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• up and down should work the way we said, and we'd like to do as little busy-waiting as possible.

Implementing Semaphores, Continued

- Idea represent semaphore as integer plus queue of waiting processes (represented as, e.g., process IDs).
- Then how should this work ...

Implementing Semaphores, Continued

• Variables — integer value, queue of process IDs queue.

• enter_cr(), leave_cr()? next slide.

Implementing Semaphores, Continued

• Revised functions to enter, leave critical region:

```
enter_cr:
   TSL registerX, lockVar
   compare registerX with 0
   if equal, jump to ok
   invoke scheduler # thread yields to another thread
   jump to enter_cr
ok:
   return

leave_cr:
   store 0 in lock
   return
```

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Minute Essay

• Alleged joke (from some random Usenet person):

A man's P should exceed his V else what's a sema for?

Do you understand this? (Remember that P is "down" and V is "up".)

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Minute Essay Answer

• It's a pun. The idea is roughly that if you never have a situation in which you've attempted more "down" operations than "up" operations, you didn't need a semaphore. (Or that's what I think it means. The author might have another idea!)