





• What if we don't know before the program starts how much memory it will want? with very old languages, maybe not an issue, but with more modern ones it is.

I.e., we might want to manage memory within a process's "address space" (range of possible program/virtual addresses).

Slide 3

• Typical scheme involves

- Fixed-size allocation for code and any static data.

- Two variable-size pieces ("heap" and "stack") for dynamically allocated data.
- Notice combined sizes of these pieces might be less than size of address space, maybe a lot less.



• Even with good choice of page size, serious performance implications — page table can still be big, and every memory reference involves page-table access — how to make this feasible/fast?

Slide 4

 (Remember that the MMU is hardware, and a bit about registers — local to the CPU, faster to access than memory but limited in number, can be general-purpose or dedicated to a particular use (e.g., the program counter).)



Large Address Spaces

- Clearly page tables can be big. How to make this feasible?
- One approach multilevel page tables.
- Another approach inverted page tables (one entry per page frame).

Slide 6







Finding A Free Frame — Page Replacement Algorithms

- Processing a page fault can involve finding a free page frame. Would be easy if the current set of processes aren't taking up all of main memory, but what if they are? Must steal a page frame from someone. How to choose one?
- Slide 10
- Several ways to make choice (as with CPU scheduling) "page replacement algorithms".
- "Good" algorithms are those that result in few page faults. (What happens if there are many page faults?)
- Choice usually constrained by what MMU provides (though that is influenced by what would help o/s designers).
- Many choices. (To be continued.)



