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Classical IPC Problems
Literature (and textbooks) on operating systems talk about "classical problems" of interprocess communication.
Idea — each is an abstract/simplified version of problems o/s designers actually need to solve. Also a good way to compare ease-of-use of various synchronization mechanisms.
Examples so far — mutual exclusion, bounded buffer.
Other examples sometimes described in silly anthropomorphic terms, but underlying problem is a simplified version of something "real".

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Dining Philosophers — Naive Solution

 Naive approach — we have five mutual-exclusion problems to solve (one per fork), so just solve them.

• Does this work? No - deadlock possible.

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Dining Philosophers — Dijkstra Solution
Another approach — use shared variables to track state of philosophers and semaphores to synchronize.
I.e., variables are

Array of five state variables (states [5]), possible values thinking, hungry, eating. Initially all thinking.
Semaphore mutex, initial value 1, to enforce one-at-a-time access to states.
Array of five semaphores self[5], initial values 0, to allow us to make philosophers wait.

And then the code is somewhat complex ...



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