

Slide 1

### Administrivia

- Homework 3 to be on Web today or tomorrow. Due next week. Basic idea is to improve your programs from Homework 2.
- Information about projects coming soon.

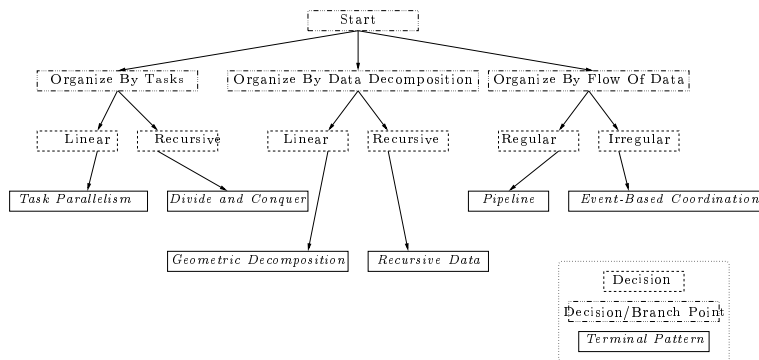
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### *Algorithm Structure Design Space*

- Historical note: These are the patterns with the longest history. We started out trying to identify commonly-used overall structures for parallel programs (these patterns), and then at some point added the other “design spaces”.
- After much thought, writing, revision, and arguing, we came up with . . .

## Algorithm Structure Decision Tree

(Figure 4.2):



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## Task Parallelism

- Problem statement:  
When the problem is best decomposed into a collection of tasks that can execute concurrently, how can this concurrency be exploited efficiently?
- Key ideas in solution — managing tasks (getting them all scheduled), detecting termination, managing any data dependencies.
- Many, many examples, including:
  - Molecular dynamics example (next slide).
  - Mandelbrot set computation.
  - Branch-and-bound computations: Maintain list of “solution spaces”. At each step, pick item from list, examine it, and either declare it a solution, discard it, or divide it into smaller spaces and put them back on list. Tasks consist of processing items from list.

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### Molecular Dynamics and Task Parallelism

- How to define tasks so we get “enough but not too many”?  
One task per atom pair is too many; one task per atom is probably right.
- How to manage data dependencies (if any)?  
Dependency involving `forces` array — potentially any UE can write to any element, if we exploit symmetry resulting from Newton’s third law. But computation is accumulation/reduction, so just give each UE a local copy and combine all copies at end.
- How to assign tasks to UEs? statically (at compile time) or dynamically (at runtime)?  
Work per task can vary, since how many atoms are “close” varies. Decide at next level.

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### Geometric Decomposition

- Problem statement:  
How can an algorithm be organized around a data structure that has been decomposed into concurrently updatable “chunks”?
- Key ideas in solution — distributing data, arranging for needed communication.
- Probably second most common pattern. Examples include:
  - Heat-diffusion problem previously discussed (next slide).
  - Matrix multiplication using blocks.

### Heat Diffusion and *Geometric Decomposition*

- How to distribute data?

One chunk per UE will probably work well. (Note that for other problems it might not.) Might be nice to include in data structure a place to store values from neighboring chunks. More in *Distributed Array*, next chapter.

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- How to synchronize/communicate?

With shared memory, just need barrier synchronization.

With distributed memory, need to exchange values with neighbor UEs, also perform reduction.

### Minute Essay

- None — sign in.

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