















Bounded	-Buffer Monitor
• Data:	
<pre>buffer B(N); // N int count = 0; condition full; condition empty;</pre>	I constant, buffer empty
Procedures:	
insert(item itm) {	remove(item &itm) {
if (count == N)	if $(count == 0)$
<pre>wait(full);</pre>	<pre>wait(empty);</pre>
<pre>put(itm, B);</pre>	<pre>itm = get(B);</pre>
count += 1;	count -= 1;
<pre>signal(empty);</pre>	signal(full);
}	}

```
SI
```





Message Passing, Continued
Exact specifications can vary, but typical assumptions include:

Sending a message never blocks a process (more difficult to implement but easier to work with).
Receiving a message blocks a process until there is a message to receive.

All messages sent are eventually available to receive (can be non-trivial to implement).
Messages from process A to process B arrive in the order in which they were sent.



Mutual Exclusion, Revisited

- How to solve mutual exclusion problem with message passing?
- Several approaches based on idea of a single "token"; process must "have the token" to enter its critical region.

(I.e., desired invariant is "only one token in the system, and if a process is in its critical region it has the token.")

- One such approach a "master process" that all other processes communicate with; simple but can be a bottleneck.
- Another such approach ring of "server processes", one for each "client process", token circulates.





