## Administrivia

- Homework 2 due date/time: Written problems due at class time; not accepted late except by prior agreement. Normal rules for programming problems apply.
- (Review minute essay from last time. Is average turnaround time the same for


## Slide 1

 all algorithms?)
## Classical IPC Problems

- Literature (and textbooks) on operating systems talk about "classical problems" of interprocess communication.
- Idea - each is an abstract/simplified version of problems o/s designers actually need to solve. Also a good way to compare ease-of-use of various synchronization mechanisms.
- Examples so far - mutual exclusion, bounded buffer.
- Other examples sometimes described in silly anthropomorphic terms, but underlying problem is a simplified version of something "real".


## Dining Philosophers Problem

- Scenario (originally proposed by Dijkstra, 1972):
- Five philosophers sitting around a table, each alternating between thinking and eating.
- Between every pair of philosophers, a fork; philosopher must have two


## Slide 3

 forks to eat.- So, neighbors can't eat at the same time, but non-neighbors can.
- Why is this interesting or important? It's a simple example of something more complex than mutual exclusion - multiple shared resources (forks), processes (philosophers) must obtain two resources together. (Why five? smallest number that's "interesting".)


## Dining Philosophers — Naive Solution

- Naive approach - we have five mutual-exclusion problems to solve (one per fork), so just solve them.
- Does this work?


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## Dining Philosophers - Simple Solution

- Another approach - just use a solution to the mutual exclusion problem to let only one philosopher at a time eat.
- Does this work?


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## Dining Philosophers - Dijkstra Solution

- Another approach - use shared variables to track state of philosophers and semaphores to synchronize.
- I.e., variables are
- Array of five state variables (states [5]), possible values

Slide 6 thinking, hungry, eating. Initially all thinking.

- Semaphore mutex, initial value 1, to enforce one-at-a-time access to states.
- Array of five semaphores self [5], initial values 0 , to allow us to make philosophers wait.
- And then the code is somewhat complex ...


## Dining Philosophers - Code

- Shared variables as on previous slide.

Pseudocode for philosopher $i$ :
while (true)
think();
down(mutex);
state[i] = hungry;
test(i);
up (mutex);
down(self[i]);
eat ();
down(mutex);
state[i] = thinking;
test(right(i));
test(left(i));
up (mutex) ;
\}
\}

## Pseudocode for function:

void test (i)
if ((state[left(i)] != eating) \&\& state[right(i) != eating) \&\& state[i] == hungry) ( state[i] = eating; state[i] = ea
up(self[i]); )
\}
up (mutex) ;

## Dining Philosophers — Dijkstra Solution Works?

- Could there be problems with access to shared state variables?
- Do we guarantee that neighbors don't eat at the same time?
- Do we allow non-neighbors to eat at the same time?
- Could we deadlock?
- Does a hungry philosopher always get to eat eventually?


## Dining Philosophers - Chandy/Misra Solution

- Original solution allows for scenarios in which one philosopher "starves" because its neighbors alternate eating while it remains hungry.
- Briefly, we could improve this by maintaining a notion of "priority" between neighbors, and only allow a philosopher to eat if (1) neither neighbor is eating, and (2) it doesn't have a higher-priority neighbor that's hungry. After a philosopher eats, it lowers its priority relative to its neighbors.
- Readers/writers (in textbook).
- Sleeping barber, drinking philosophers, ...
- Advice - if you ever have to solve problems like this "for real", read the literature...


## Minute Essay

- Any questions about material in chapter 2 (processes, threads, synchronization, scheduling)?


## Slide 11

