



# More Differential Equations

10-2-2006





# Opening Discussion

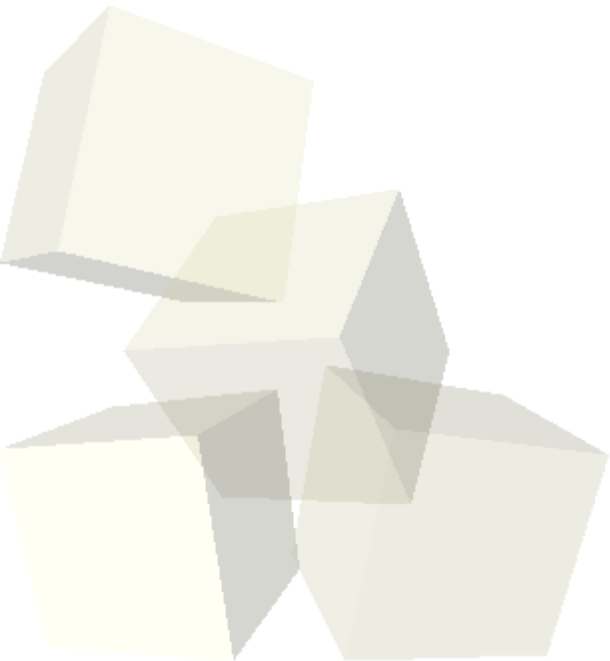
- What did we talk about last class?
- Do you have any questions about the assignment?





# Finishing Off Euler's Method

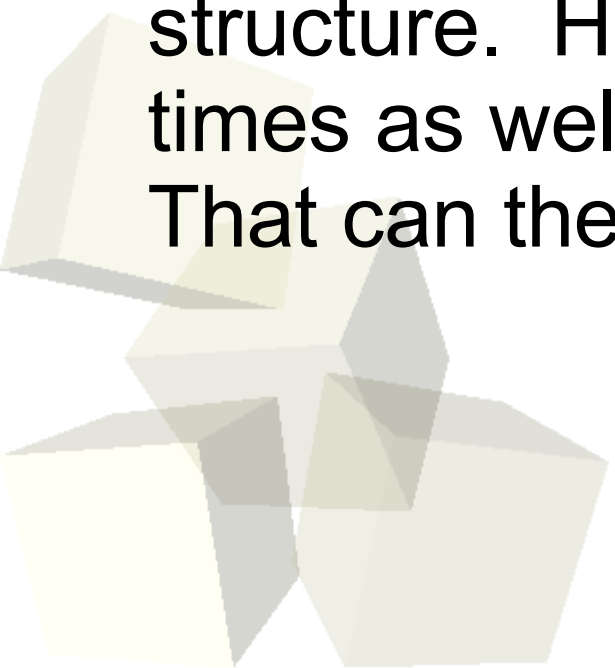
- Last time we started writing an Euler's method to demonstrate to you the making of a simple integrator. We need to finish that and use it to integrate a problem.
- The simplest problem to solve is the mass on a spring with Hook's Law. We'll do that first.





# Using the ode Functions

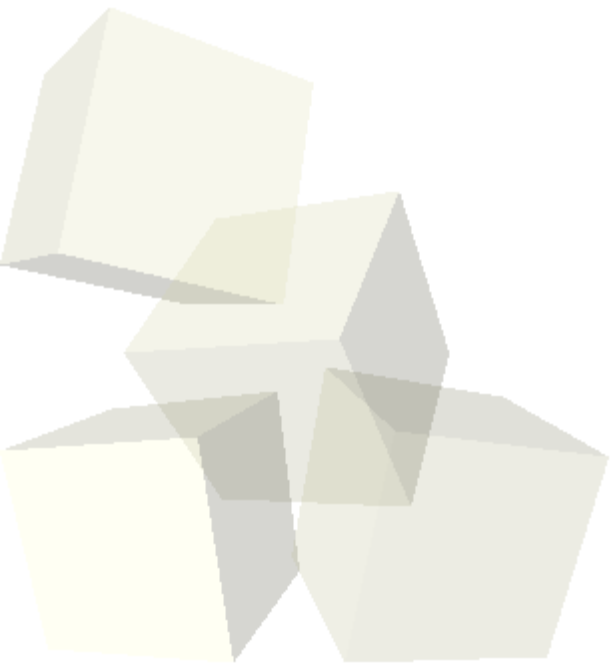
- In order to use ode45 or other ODE solving functions, we must define our function in an m-file because we want to pass a handle to it into the ode function. This function should return the derivatives as a column vector.
- If we don't use any return values the function will simply show a plot. A single return value returns a structure. Having two return values gives us the times as well as the arrays of values at each time. That can then be plotted as we see fit.





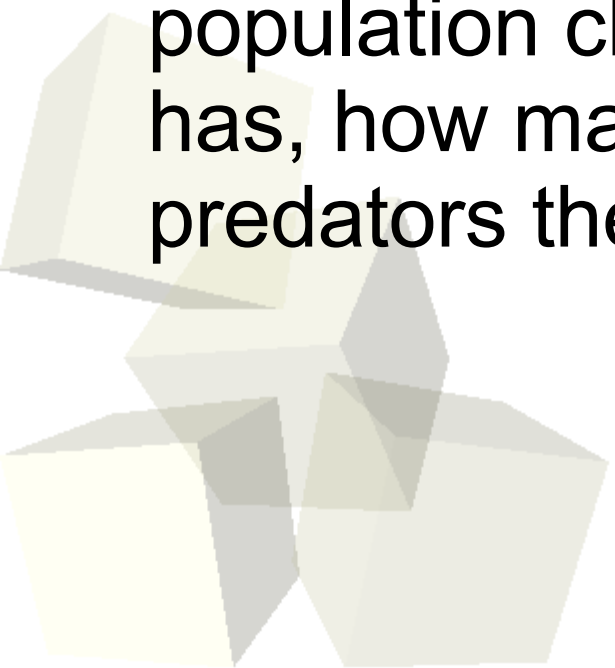
# Multibody Systems as ODEs

- So how do we represent a multibody system as an ODE? What are the variables that we need? What does the system of equations look like?
- The simplest system is probably gravity. Let's set up an N-body gravitational system and solve it with ode45.





- ODEs abound in physics. The simplest ones involve solving the paths of particles interacting through a force like gravity or having masses on springs.
- Population biology can also be expressed as differential equations. Consider things like predator-prey models where how quickly a population changes depends on how much food it has, how many there are now, and how many predators there are.





- Assignment #5 is due on Wednesday and Quiz #3 will be on Friday.
- Next week there won't be any class, but you should be working on the project.
- We will talk about the project in more detail on Wednesday.

